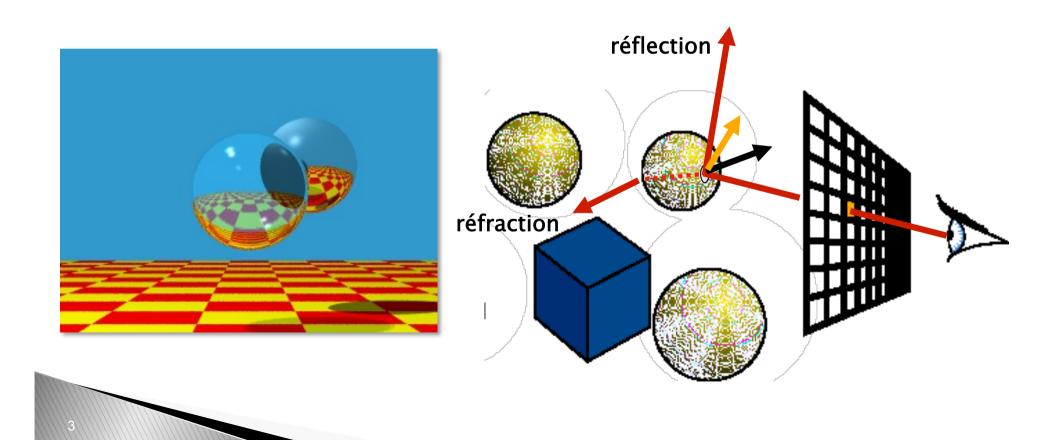
# Ray-tracing

### Ray-tracing

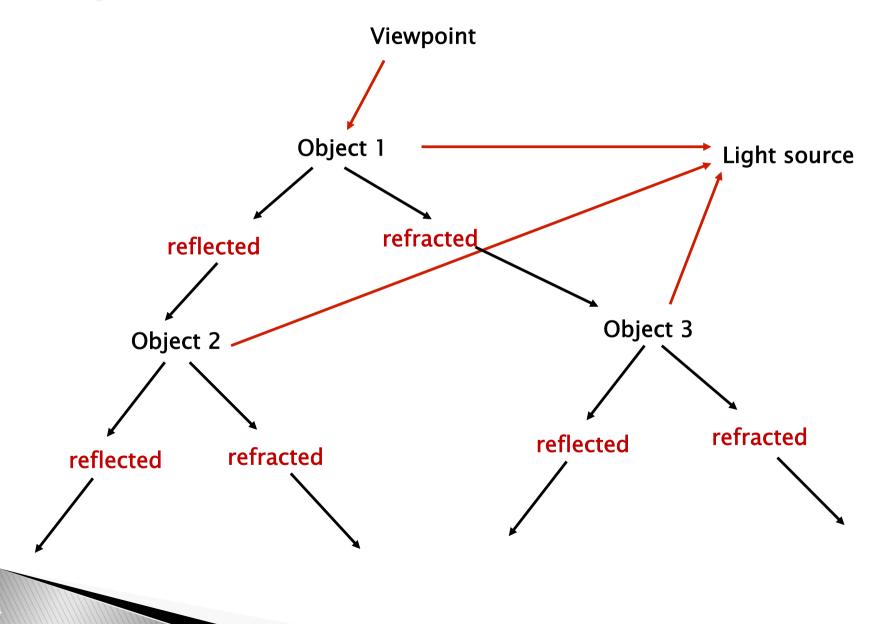
- Ray casting, ray tracing: rays sent from view point towards the scene.
- One ray for every pixel.
- Pixel color depends on illumination at the first surface intersected by the ray
- Using local illumination models

#### Extension

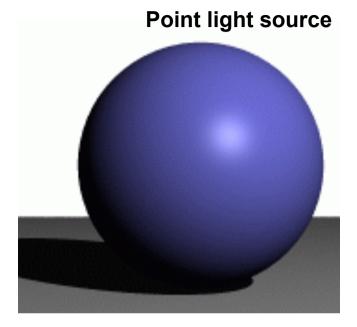
Three new rays are generated: refracted ray, reflected ray, shadow ray

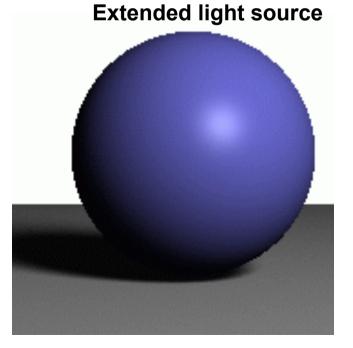


## Ray-tree



- Soft shadows
  - Several shadow rays for each extended light source

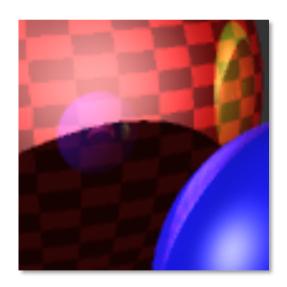




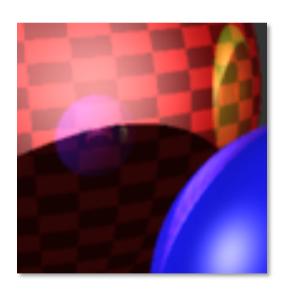
- Soft shadows
  - Several shadow rays for each extended light source
- Anti-aliasing
  - Several rays per pixel





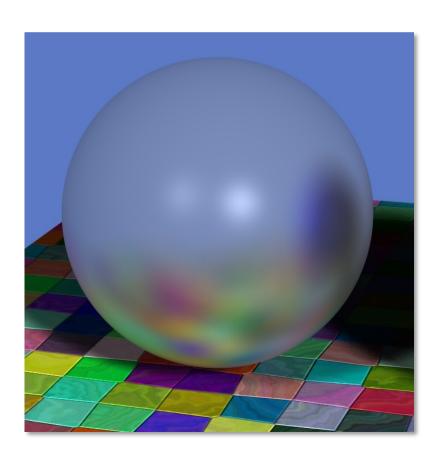


2 rayons



3 rayons

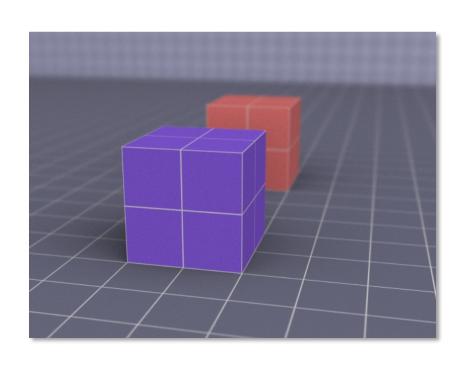
- Soft shadows
  - Several shadow rays for each extended light source
- Anti-aliasing
  - Several rays per pixel
- Glossy reflections
  - Several reflected rays



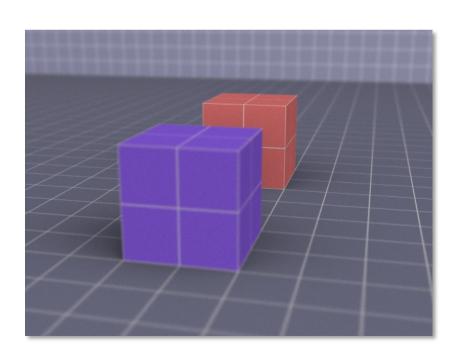
- Soft shadows
  - Several shadow rays for each extended light source
- Anti-aliasing
  - Several rays per pixel
- Glossy reflections
  - Several reflected rays
- Motion blur
  - Several rays through time



- Soft shadows
  - Several shadow rays for each extended light source
- Anti-aliasing
  - Several rays per pixel
- Glossy reflections
  - Several reflected rays
- Motion blur
  - Several rays through time
- Depth of field
  - Several rays per pixel through the lens



- Soft shadows
  - Several shadow rays for each extended light source
- Anti-aliasing
  - Several rays per pixel
- Glossy reflections
  - Several reflected rays
- Motion blur
  - Several rays through time
- Depth of field
  - Several rays per pixel through the lens



#### Ray-scene intersection

- Ray-sphere: point-line distance.
- Ray-cylinder: line-line distance.
- Ray-plane: line-plane intersection
- ▶ Ray-polygon:
  - line-plane intersection.
  - test whether intersection point is in polygon:
    - project onto xy plane, check inside 2D polygon.

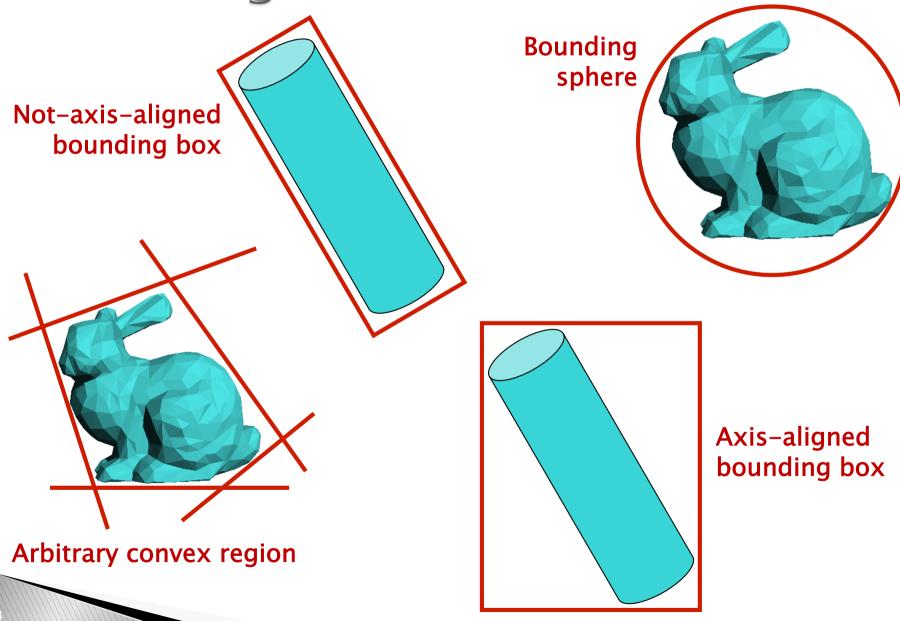
#### Ray-scene intersection

- ▶ 99 % of the time is spent doing intersections.
- Need for accelerations:
  - bounding volumes,
  - uniform grids (voxels),
  - octrees,
  - BSP-trees,
  - problem specific accelerations;

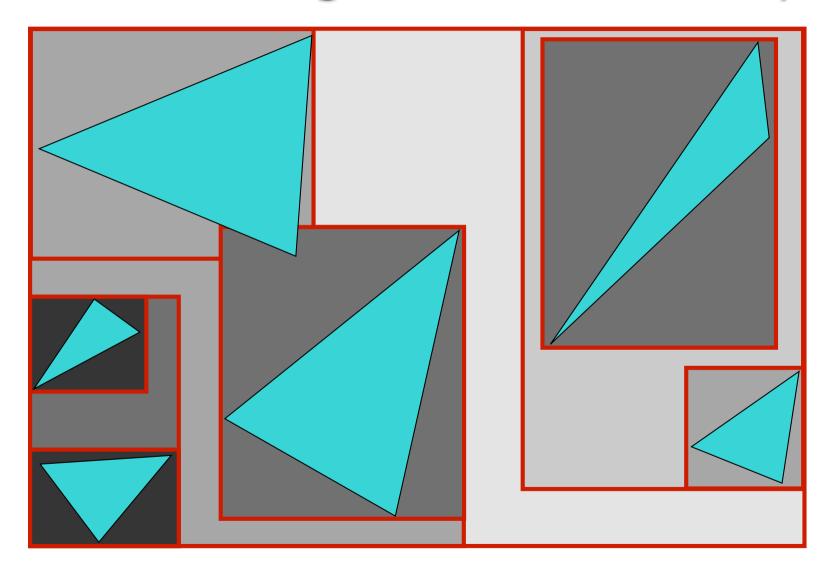
## Bounding volumes

▶ Intersection with a bounding volume Early rejection

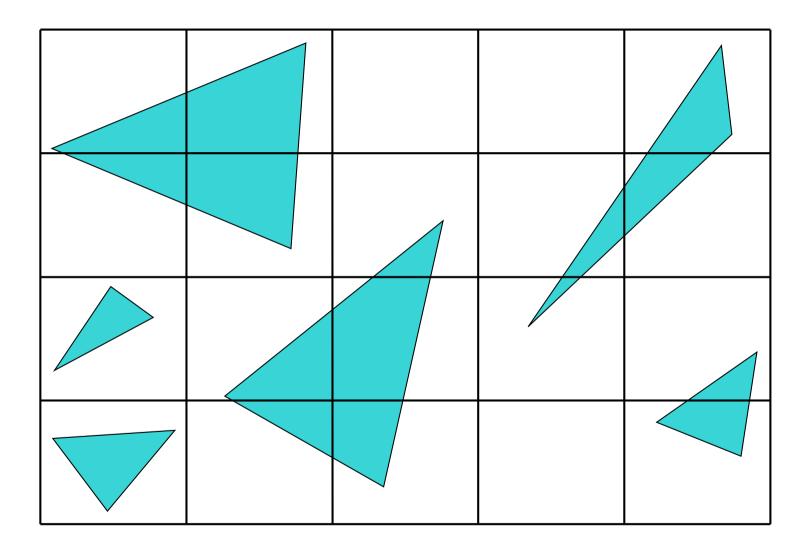
## Bounding volumes



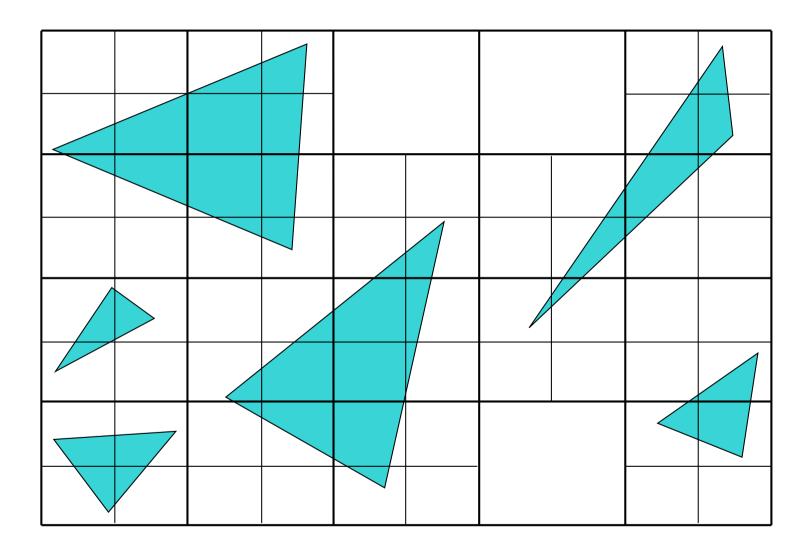
## BVH: Bounding Volume Hierarchy



## Uniform grid



## Adaptive grid: Octree



#### Question. 3 mn with your neighbors

- ▶ Compare 3 accelerations structures:
  - Bounding volumes
  - Uniform grid
  - Octree



### Comparison

- ▶ Bounding volume:
  - long initial step, fast requests.
- Uniform Grid:
  - fast initial step, fast requests... if proper resolution.
- Octrees:
  - fast and simple initial step, longer requests.

### Ray-tracing: advantages

- Slow, but no extra charge for:
  - hidden surface removal,
  - shadows,
  - transparency,
  - texture-mapping (including procedural).
- Inter-reflexions between objects,
- Any graphics primitives,
- Global illumination model.

### Ray-tracing: issues

- Limited to Snell-Descartes:
  - all objects are metallic.
- Tree limited to a certain depth:
  - complex objects may be a problem (diamonds, cristal glass)
- Extension: Monte-Carlo Ray-Tracing
  - shoots several rays. slow, but nice.